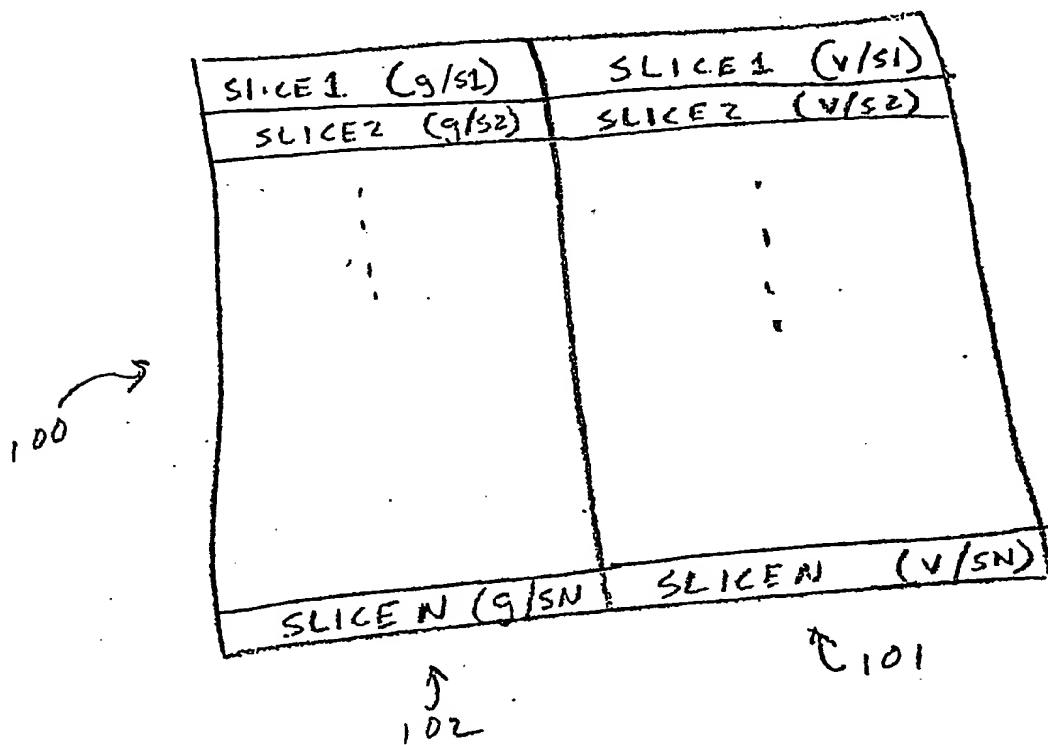


Figure 2



A hand-drawn diagram showing a table with two columns and multiple rows. The table is tilted slightly to the right. The columns are labeled 'SLICE 1 (g/s1)' and 'SLICE 1 (v/s1)' in the top row, 'SLICE 2 (g/s2)' and 'SLICE 2 (v/s2)' in the second row, and 'SLICE N (g/sN)' and 'SLICE N (v/sN)' in the bottom row. The table is divided into two main sections by a vertical line. The left section contains three rows of data, and the right section contains three rows of data. An arrow labeled '100' points to the left side of the table. An arrow labeled '102' points to the bottom of the table. An arrow labeled '101' points to the right side of the table.

SLICE 1 (g/s1)	SLICE 1 (v/s1)
SLICE 2 (g/s2)	SLICE 2 (v/s2)
SLICE N (g/sN)	SLICE N (v/sN)

FIGURE 3

216

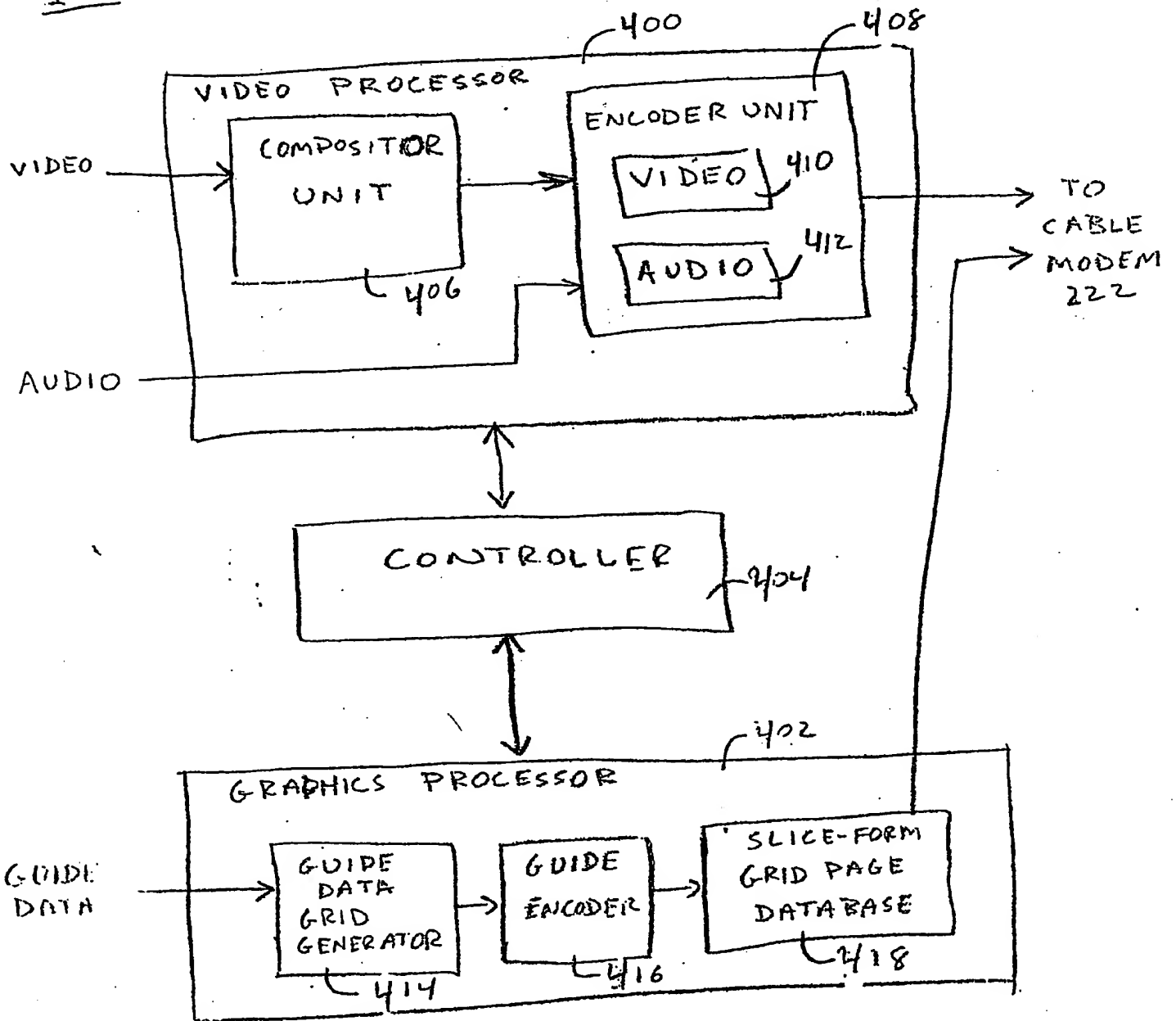


FIGURE 4

228

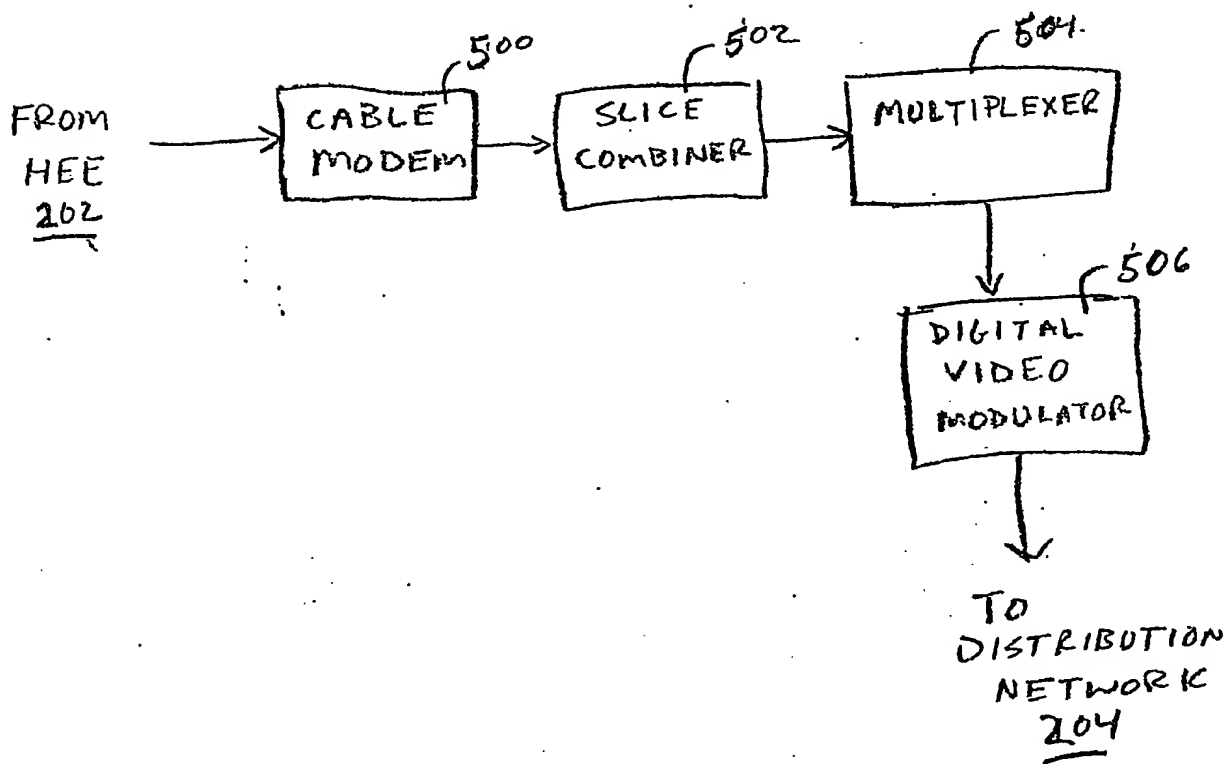


FIGURE 5

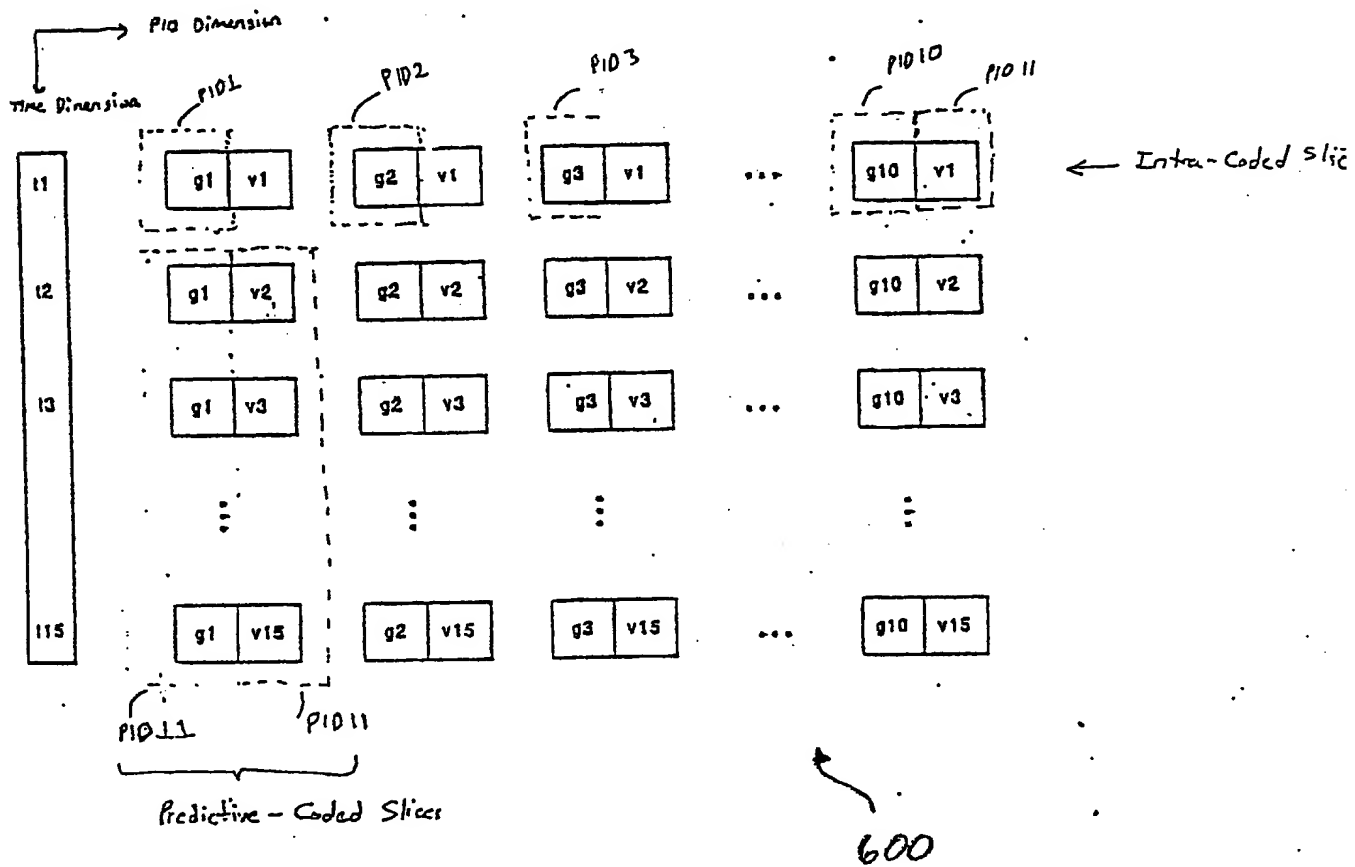


Figure 6

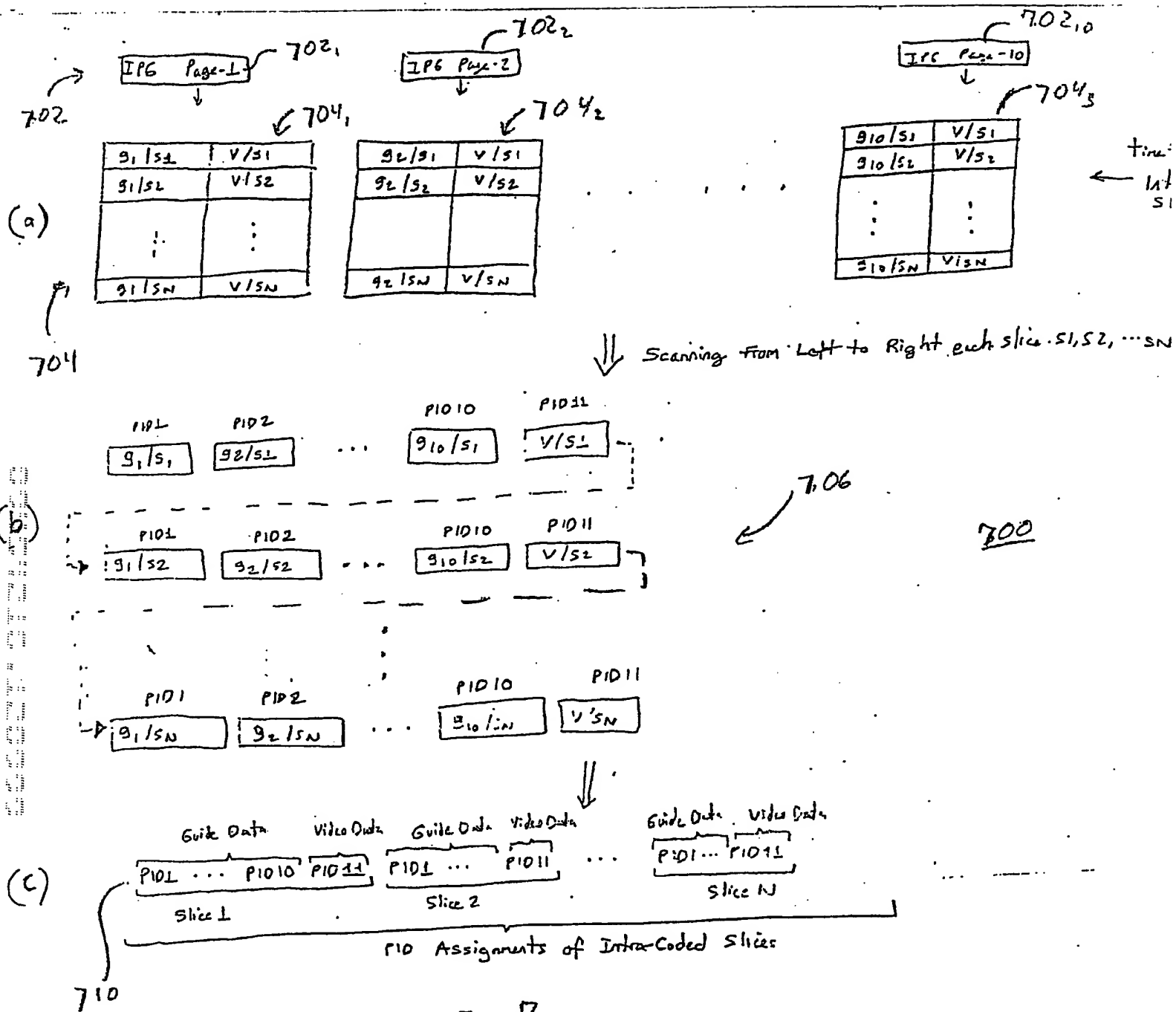
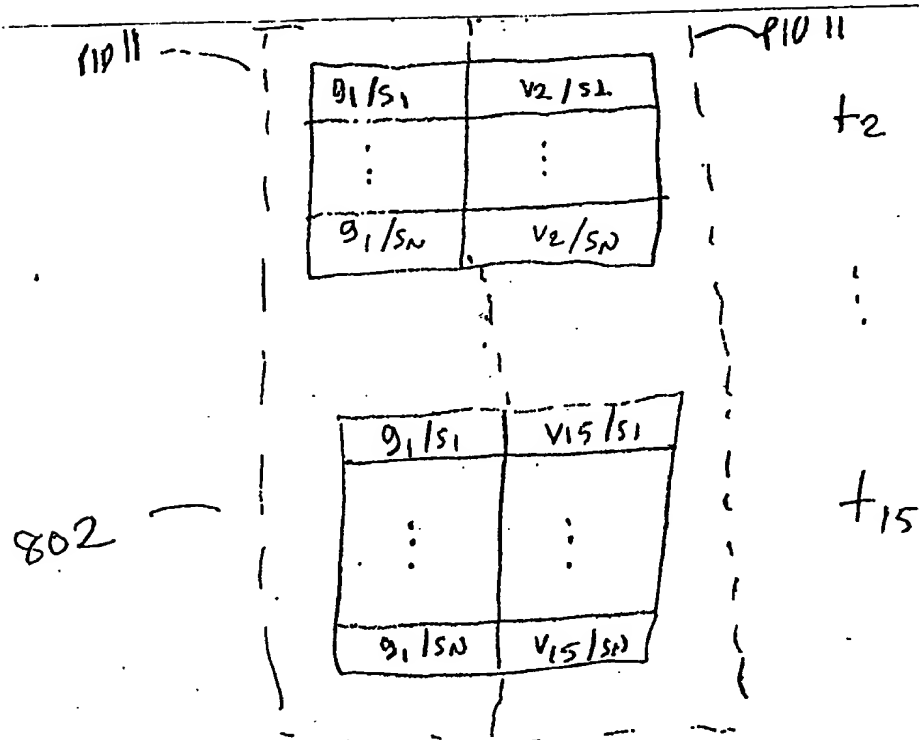
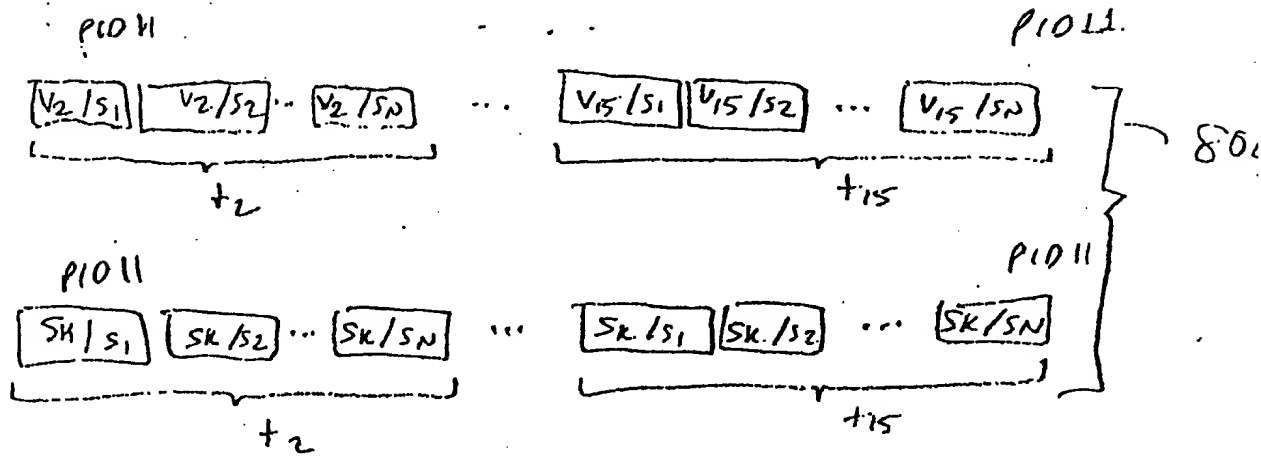


Figure 7



Scanning Video Slices  
from left to right  
top to bottom



Skipped  
Guide  
Slices

800

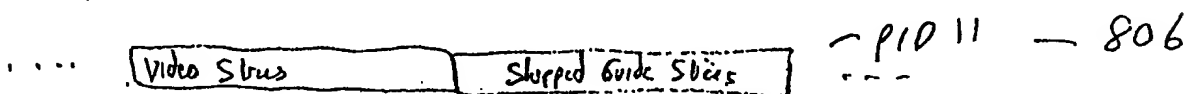


Figure 8



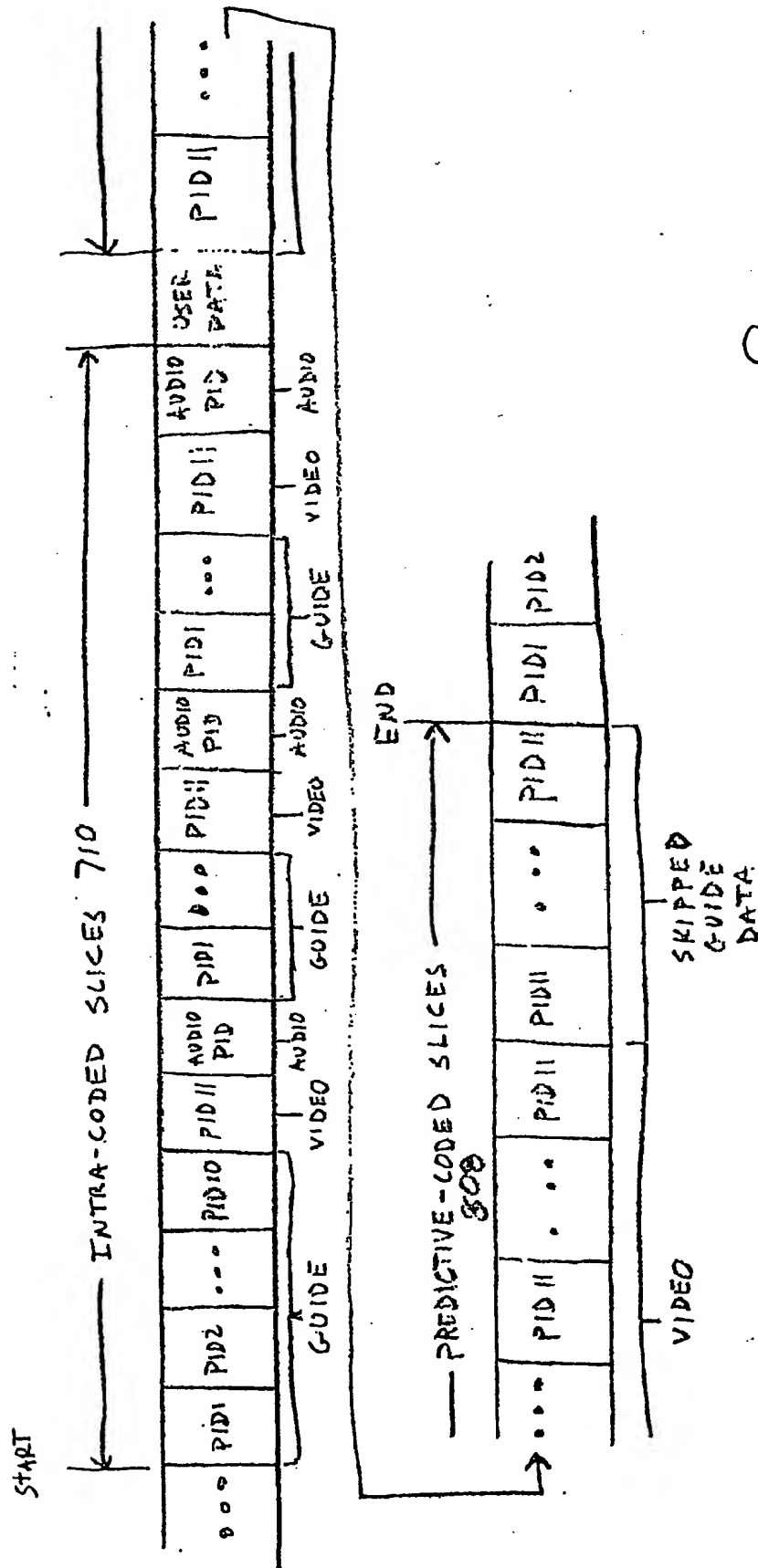


Figure 9

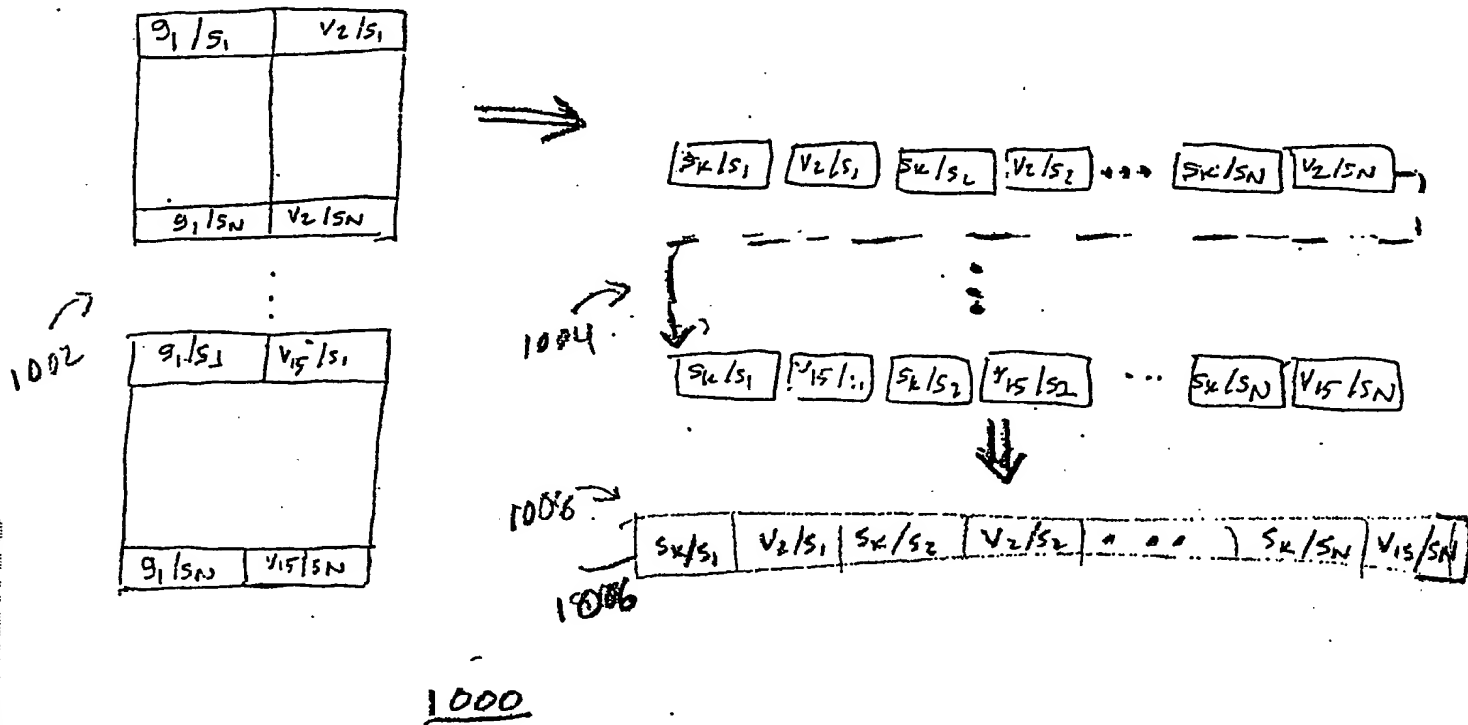


Figure 10

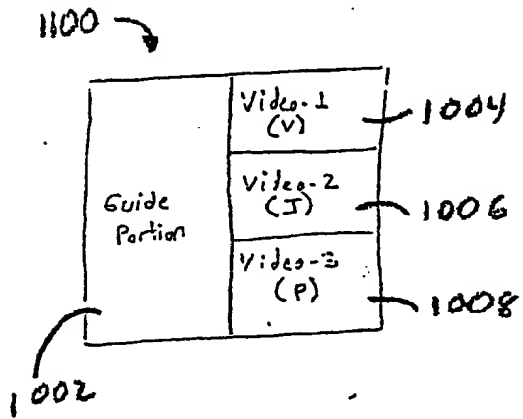


FIGURE 11A

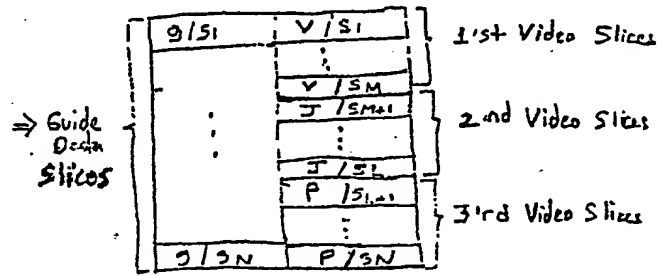


Figure 11B

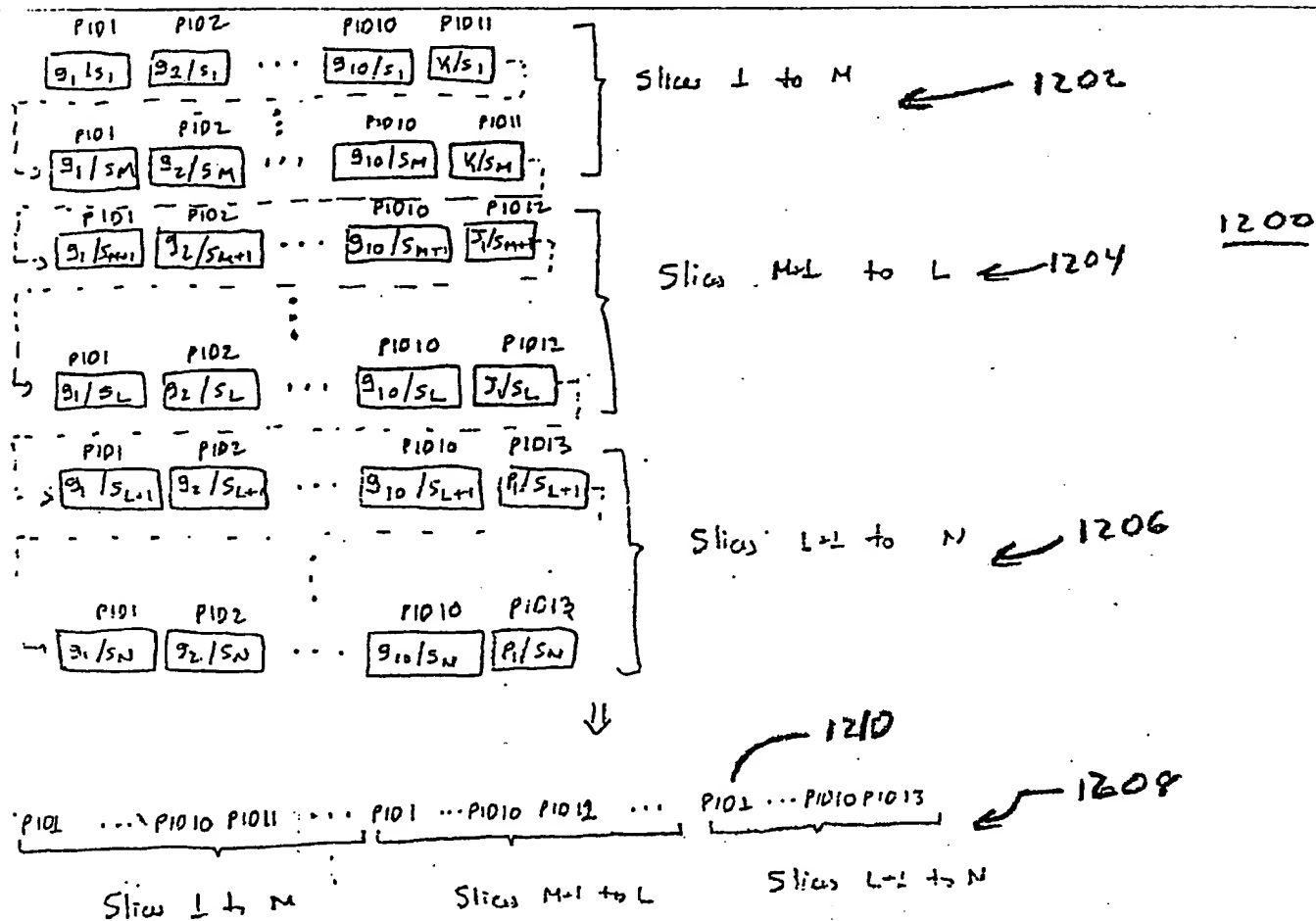


Figure 12

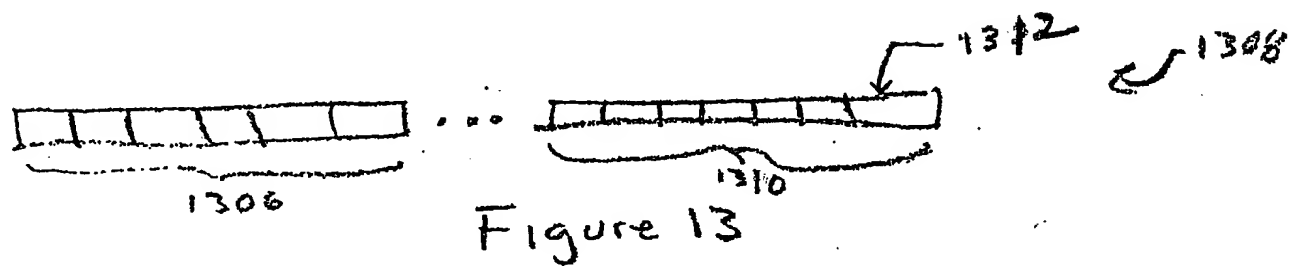
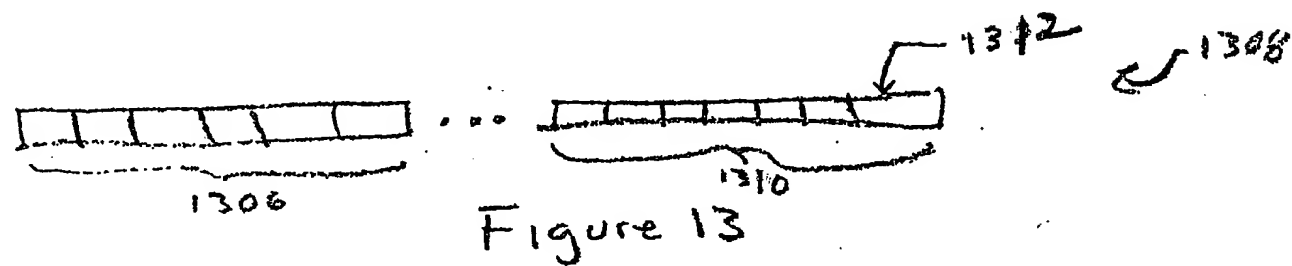
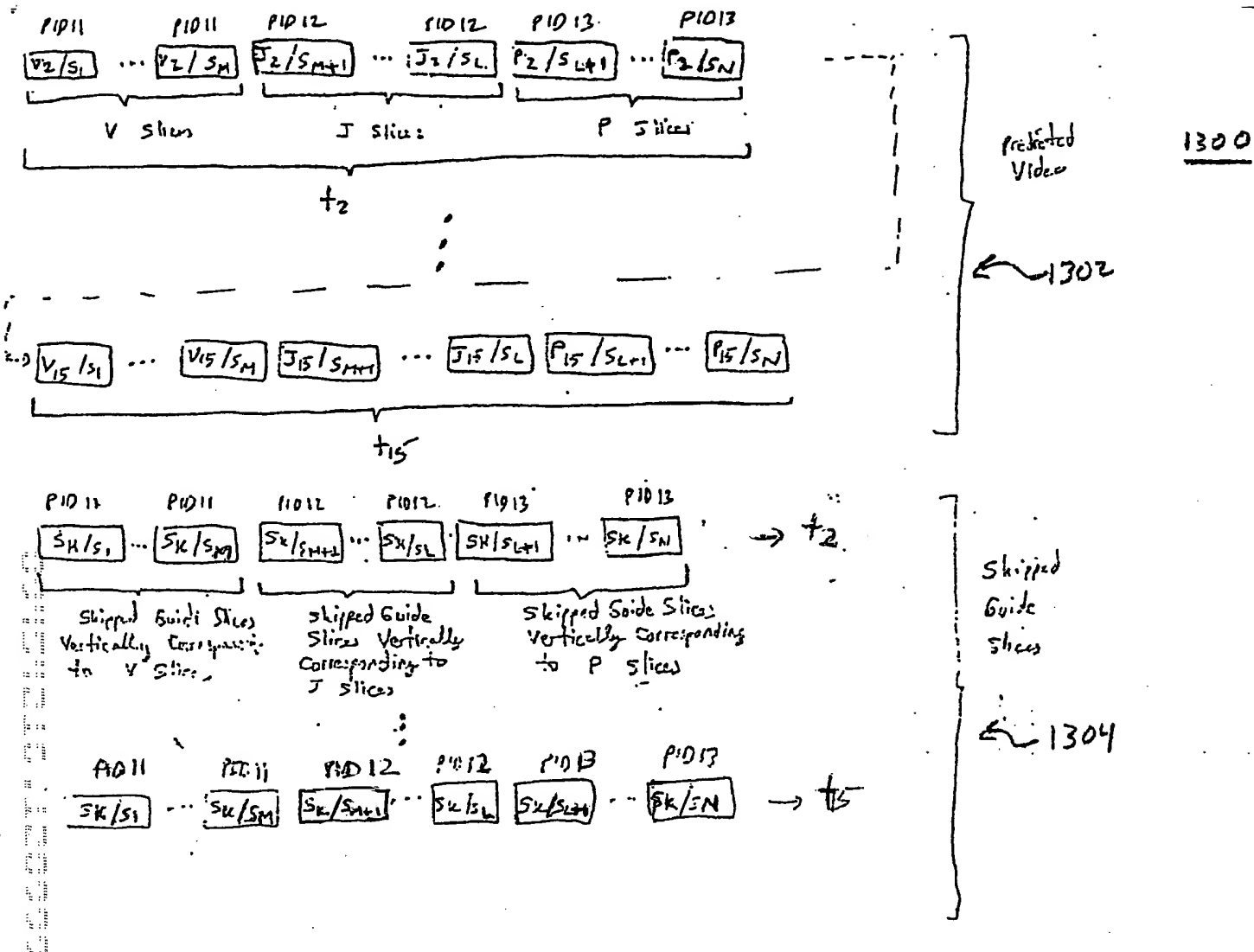


Figure 13

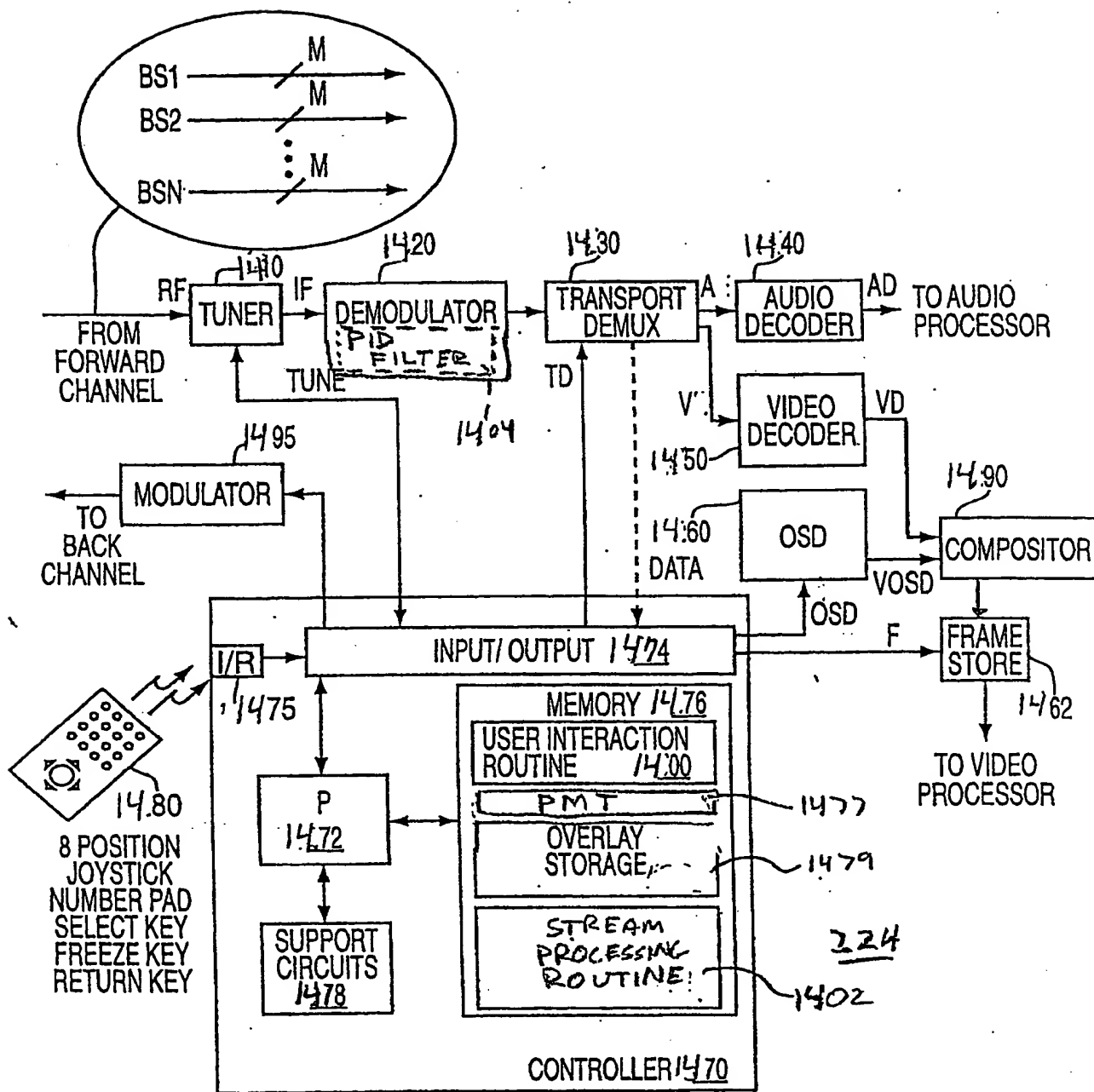


Figure 14

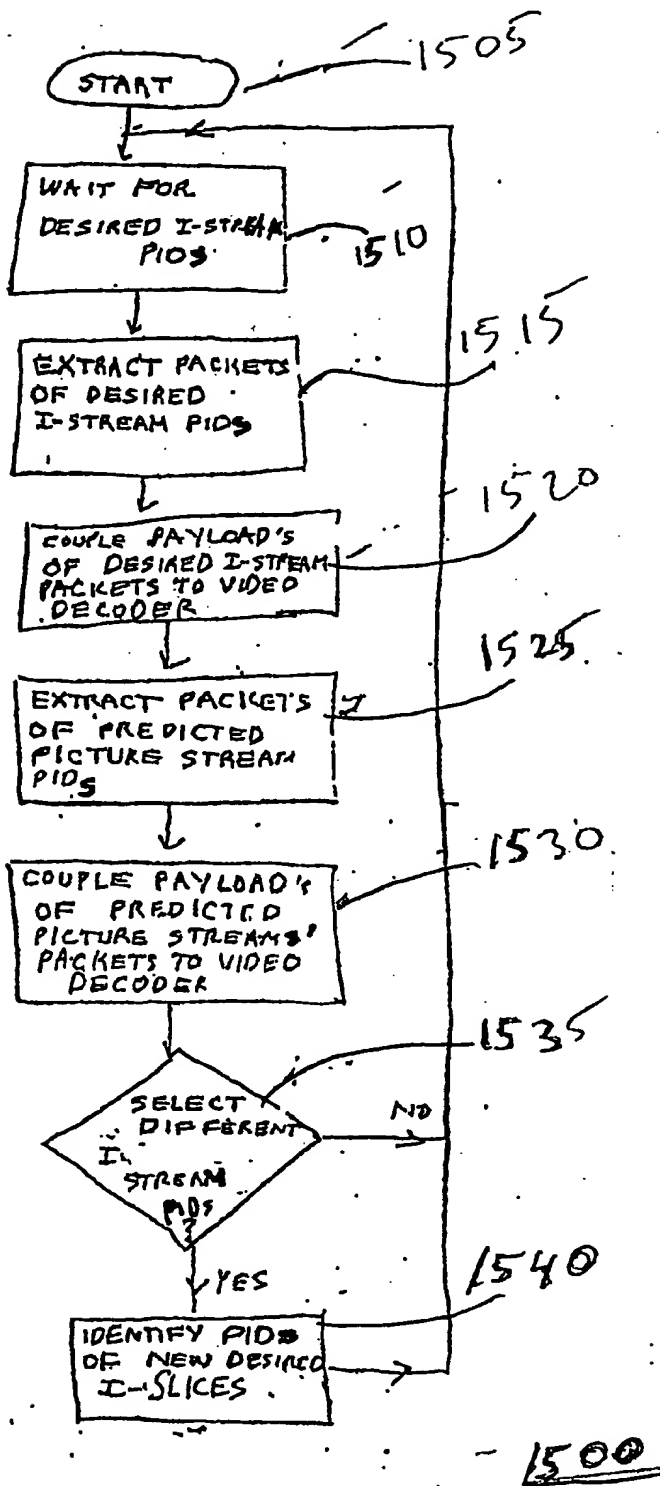


Figure 15

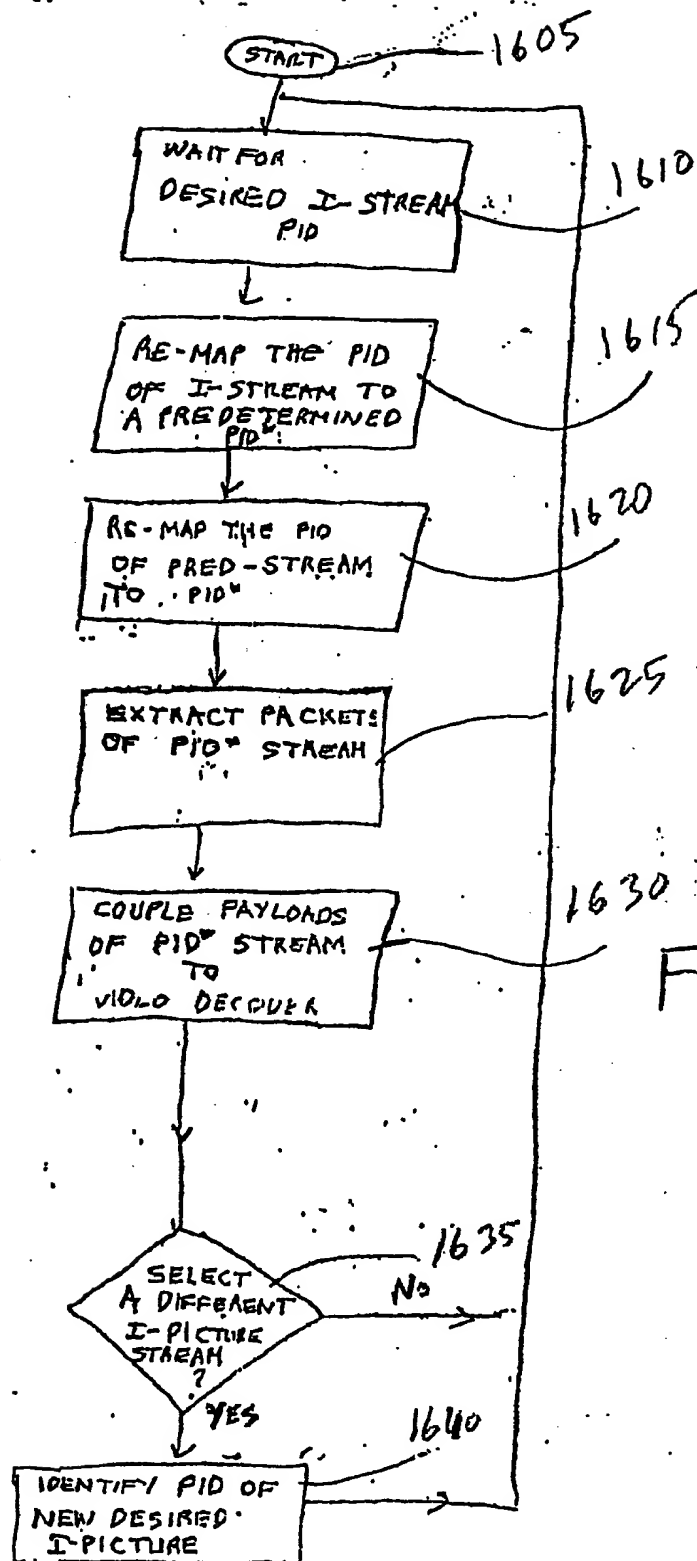


Figure 16



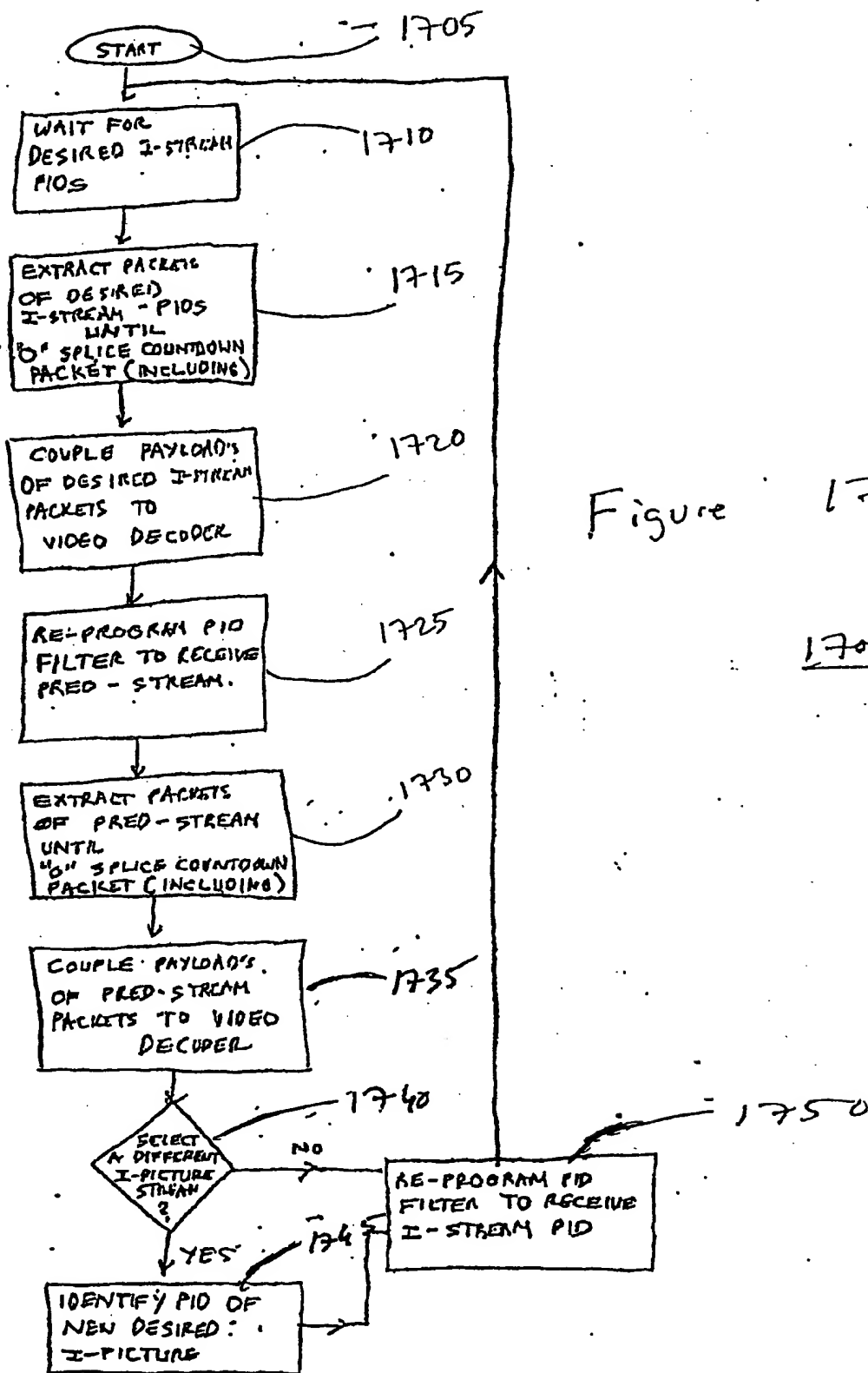


Figure 17

1700

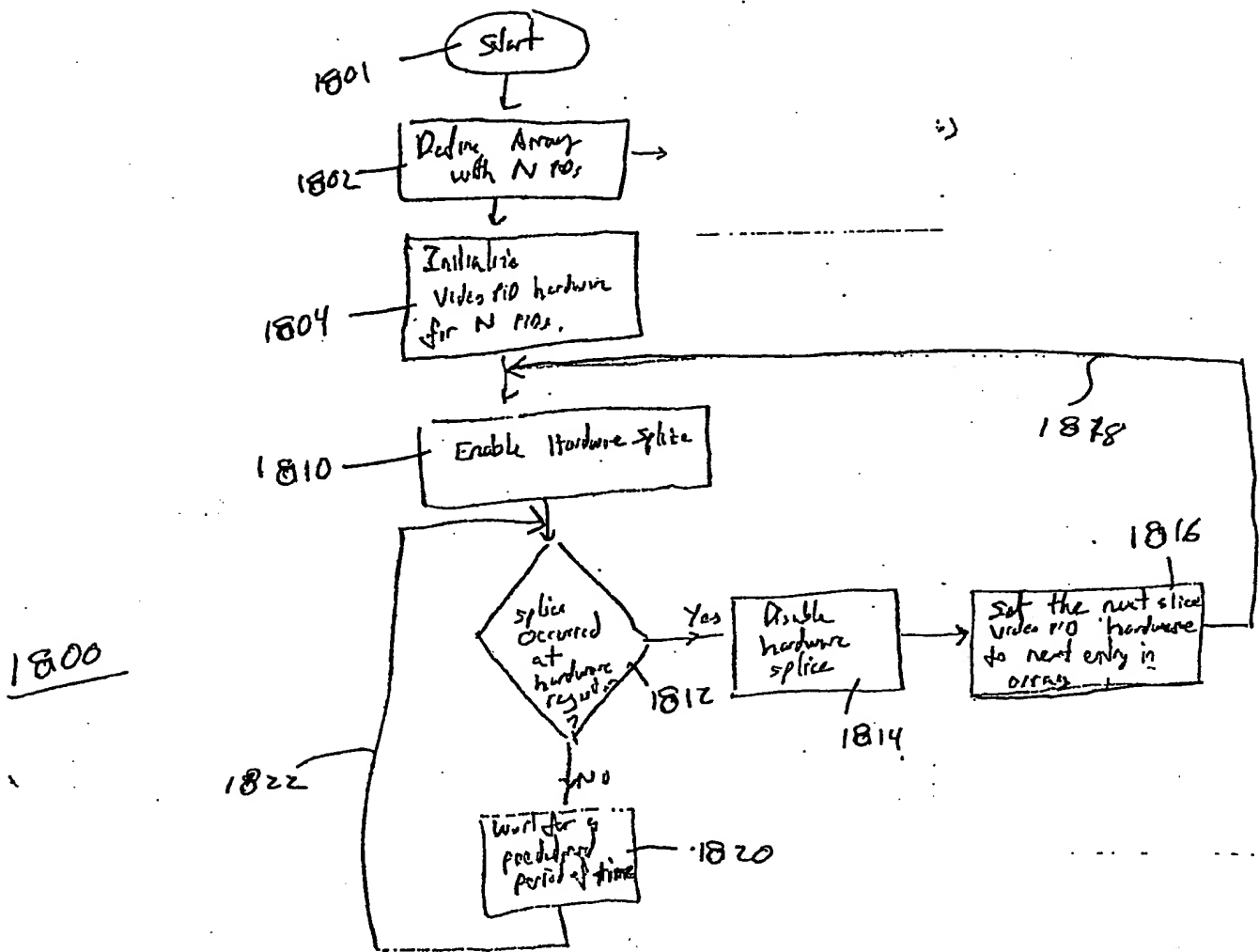


Figure 18

time =  $t_1$

<u>PID1</u>	<u>PID2</u>	<u>PID3</u>	...	<u>PID9</u>	<u>PID10</u>	<u>PID11</u>	<u>PID12</u>	<u>PID13</u>
$g1/s1$	$g2/s1$	$g3/s1$	...	$g9/s1$	$g10/s1$	$v1/s1$	$m1/s1$	$k1/s1$
$g1/s2$	$g2/s2$	$g3/s2$	...	$g9/s2$	$g10/s2$	$v1/s2$	$m1/s2$	$k1/s2$
$g1/s3$	$g2/s3$	$g3/s3$	...	$g9/s3$	$g10/s3$	$v1/s3$	$m1/s3$	$k1/s3$
$\vdots$	$\vdots$	$\vdots$		$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$
$\vdots$	$\vdots$	$\vdots$		$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$
$\vdots$	$\vdots$	$\vdots$		$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$
$\hookrightarrow g1/sN$	$g2/sN$	$g3/sN$	...	$g9/sN$	$g10/sN$	$v1/sN$	$m1/sN$	$k1/sN$

~ 1900

Intra-coded Guide and Video

Fig. 19

1. The first part of the figure shows the predicted video signal for the first 1000 samples of the video signal. The second part shows the predicted video signal for the next 1000 samples. The third part shows the predicted video signal for the next 1000 samples. The fourth part shows the predicted video signal for the next 1000 samples. The fifth part shows the predicted video signal for the next 1000 samples. The sixth part shows the predicted video signal for the next 1000 samples. The seventh part shows the predicted video signal for the next 1000 samples. The eighth part shows the predicted video signal for the next 1000 samples. The ninth part shows the predicted video signal for the next 1000 samples. The tenth part shows the predicted video signal for the next 1000 samples.

<u>time</u>	<u>PID 11</u>	<u>PID 12</u>	<u>PID 13</u>	<u>PID 11</u>	<u>PID 12</u>	<u>PID 13</u>	<u>PID 12</u>	<u>PID 13</u>	<u>2000</u>
$x_2$	$V_2/S_1$	$M_2/S_1$	$K_2/S_1$	$V_2/S_2$	$M_2/S_2$	$K_2/S_2$	$V_2/SN$	$M_2/SN$	$K_2/SN$
$x_3$	$V_3/S_1$	$M_3/S_1$	$K_3/S_1$	$V_3/S_2$	$M_3/S_2$	$K_3/S_2$	$V_3/SN$	$M_3/SN$	$K_3/SN$
$x_4$	$V_4/S_1$	$M_4/S_1$	$K_4/S_1$	$V_4/S_2$	$M_4/S_2$	$K_4/S_2$	$V_4/SN$	$M_4/SN$	$K_4/SN$
$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$
$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$
$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$
$x_{15}$	$V_{15}/S_1$	$M_{15}/S_1$	$K_{15}/S_1$	$V_{15}/S_2$	$M_{15}/S_2$	$K_{15}/S_2$	$V_{15/SN}$	$M_{15/SN}$	$K_{15/SN}$

Predicted Video 2000

Fig. 20

time	PID11	PID12	PID13	PID11	PID12	PID13	PID11	PID12	PID13
$t_2$	SK/S1	SK/S1	SK/S1	SK/S2	SK/S2	SK/S2	SK/SN	SK/SN	SK/SN
$t_3$	SK/S1	SK/S1	SK/S1	SK/S2	SK/S2	SK/S2	SK/SN	SK/SN	SK/SN
$t_4$	SK/S1	SK/S1	SK/S1	SK/S2	SK/S2	SK/S2	SK/SN	SK/SN	SK/SN
$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$
$t_{15}$	SK/S1	SK/S1	SK/S1	SK/S1	SK/S2	SK/S2	SK/SN	SK/SN	SK/SN

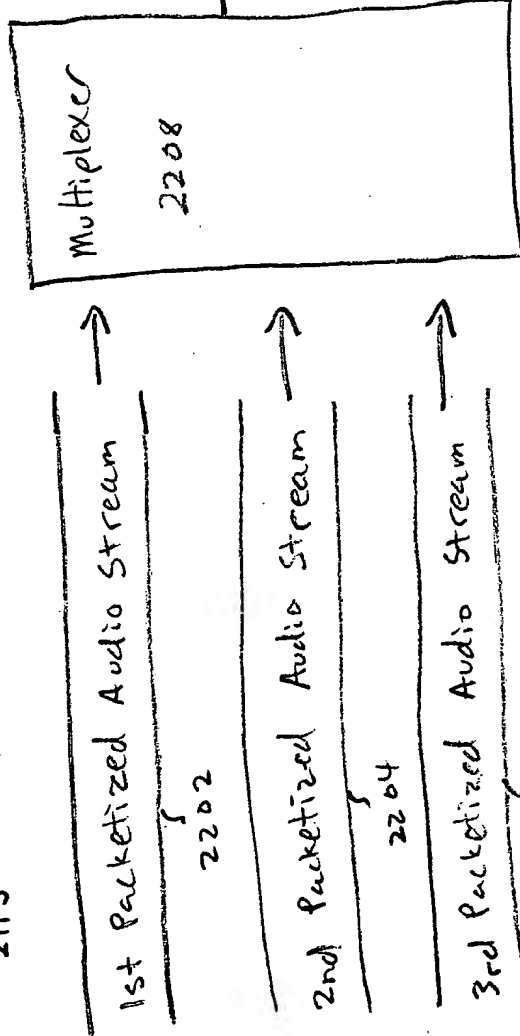
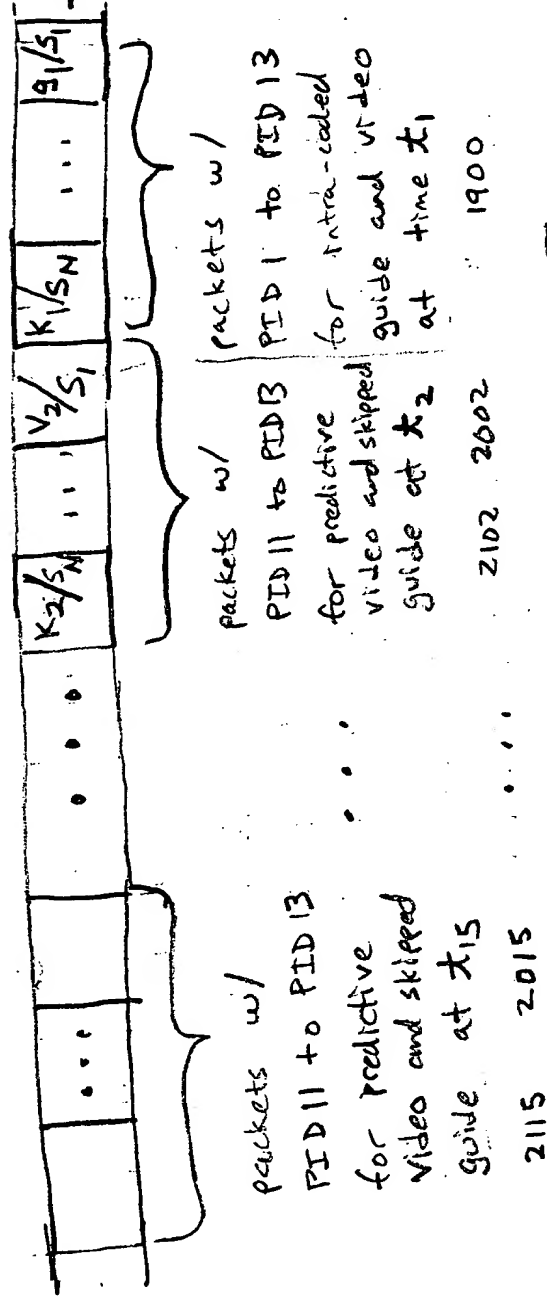
2100

Skipped Guide

Fig. 21

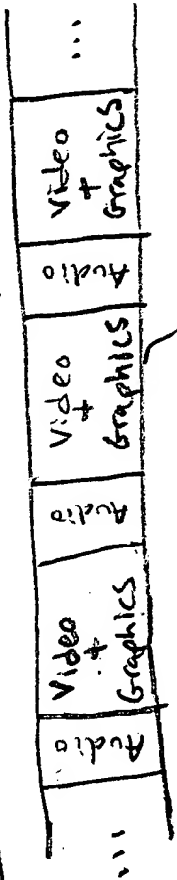
# Video and Graphics

2214



2210

2216



Transport Stream

Fig. 22

$O_1$	$O_2$	$O_3$
$O_4$	$O_5$	$O_6$
$O_7$	$O_8$	$O_9$

objects

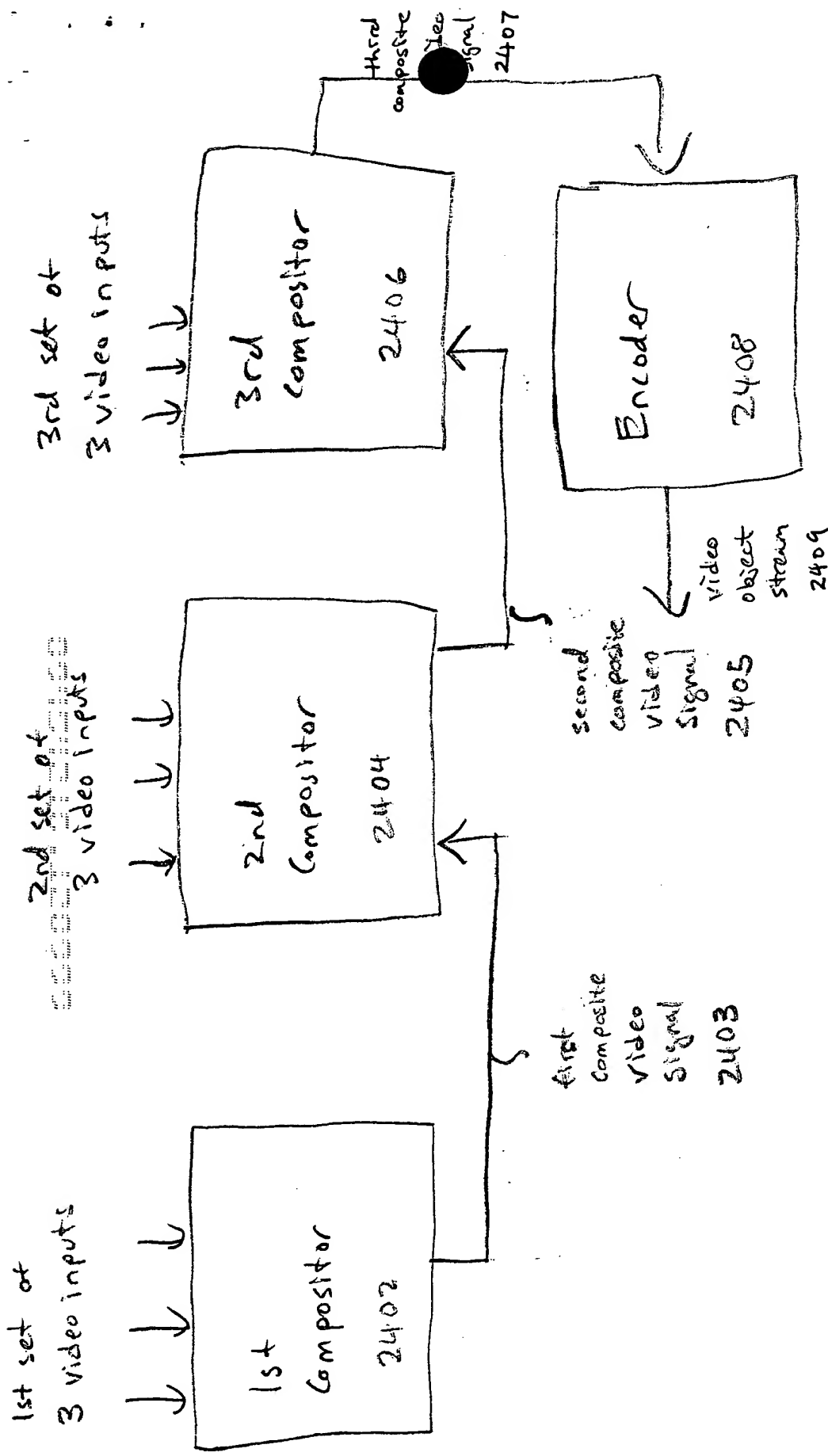
(a)

$O_1/S_1$	$O_2/S_1$	$O_3/S_1$
$\vdots$	$\vdots$	$\vdots$
$O_1/S_N$	$O_2/S_N$	$O_3/S_N$
$O_4/S_{N+1}$	$O_5/S_{N+1}$	$O_6/S_{N+1}$
$\vdots$	$\vdots$	$\vdots$
$O_4/S_{2N}$	$O_5/S_{2N}$	$O_6/S_{2N}$
$O_7/S_{2N+1}$	$O_8/S_{2N+1}$	$O_9/S_{2N+1}$
$\vdots$	$\vdots$	$\vdots$
$O_7/S_{3N}$	$O_8/S_{3N}$	$O_9/S_{3N}$

slice-based partitioning

(b)

Fig. 23



Cascade Compositor

Fig. 24



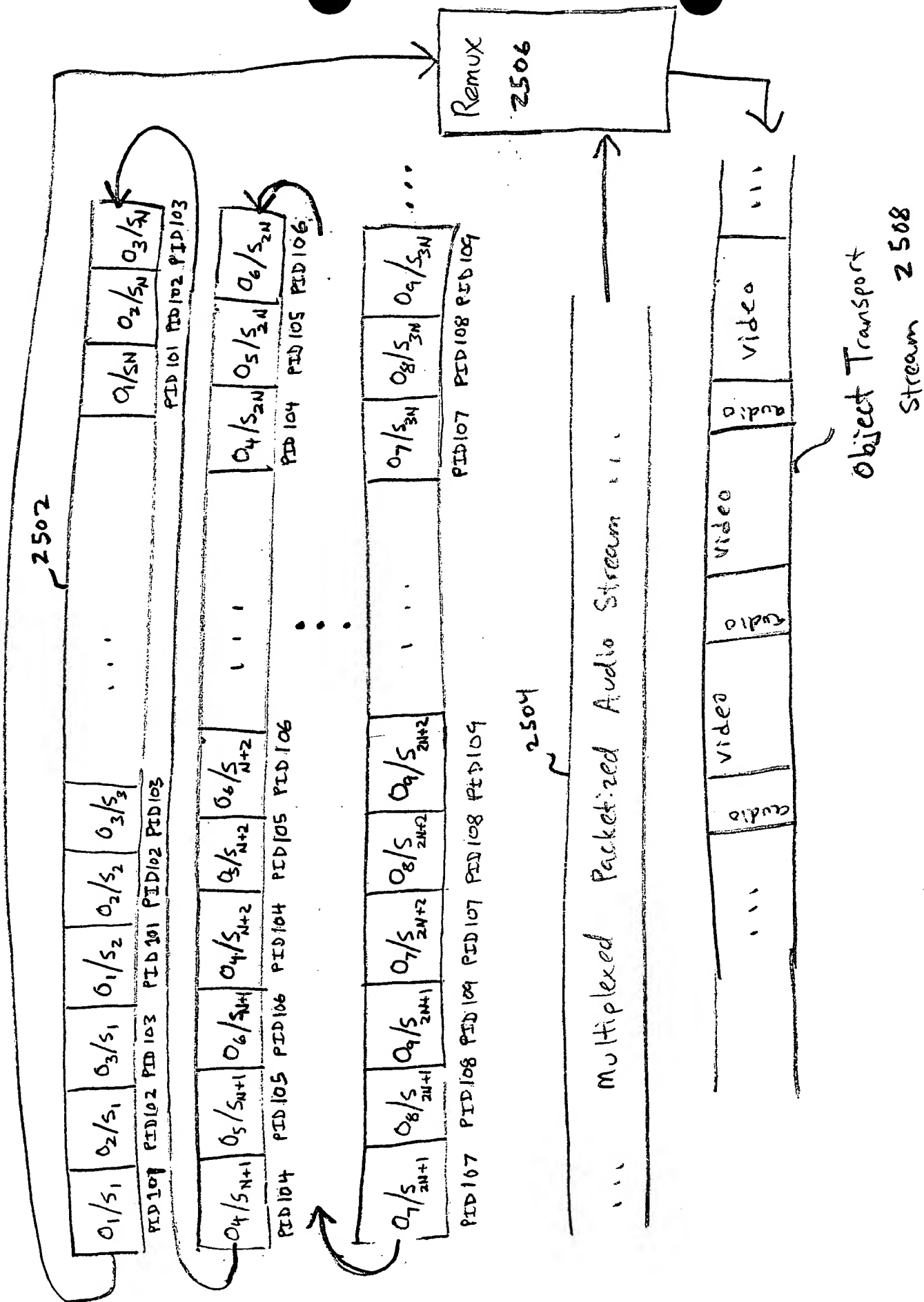


Fig. 25

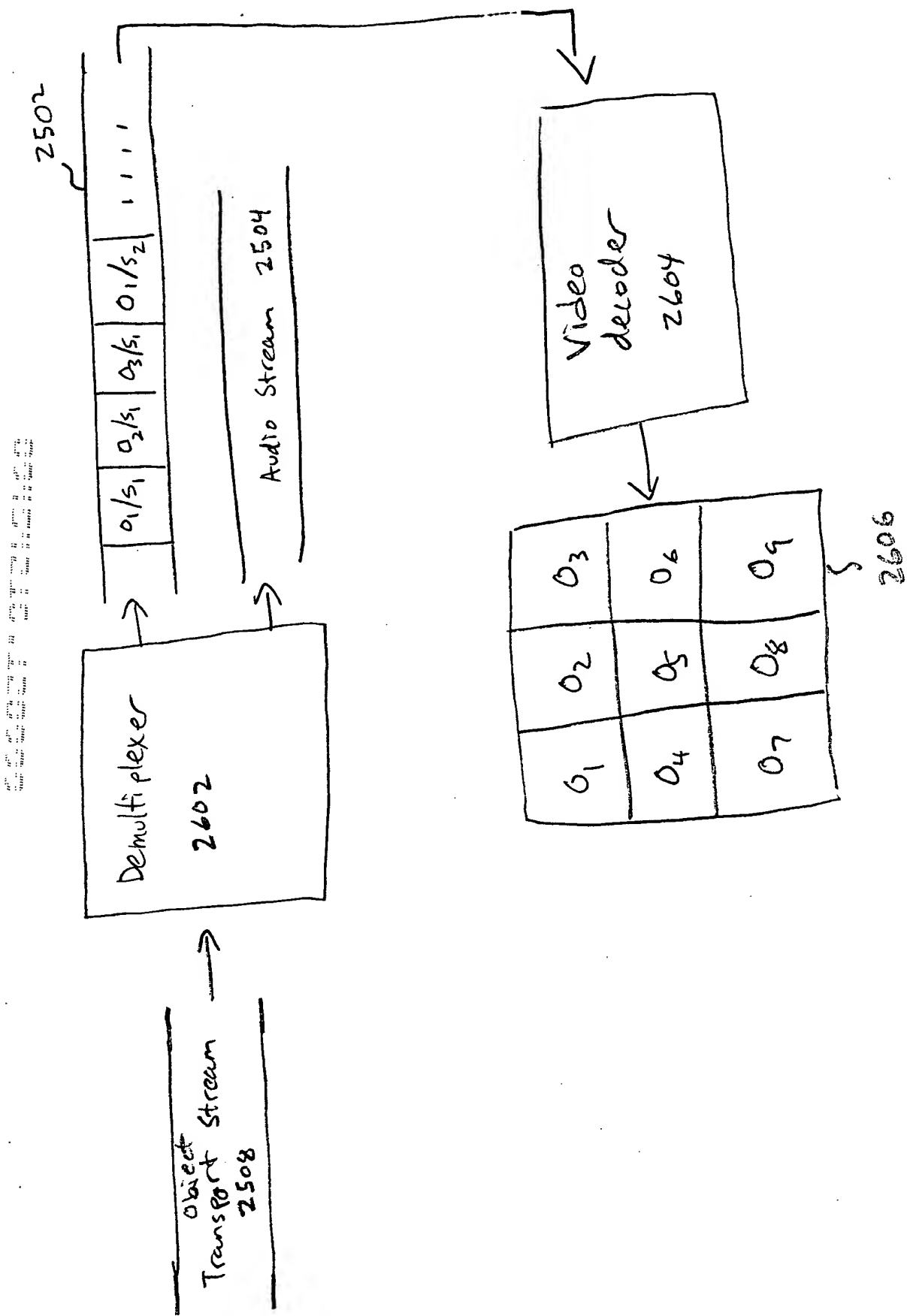


Fig. 26

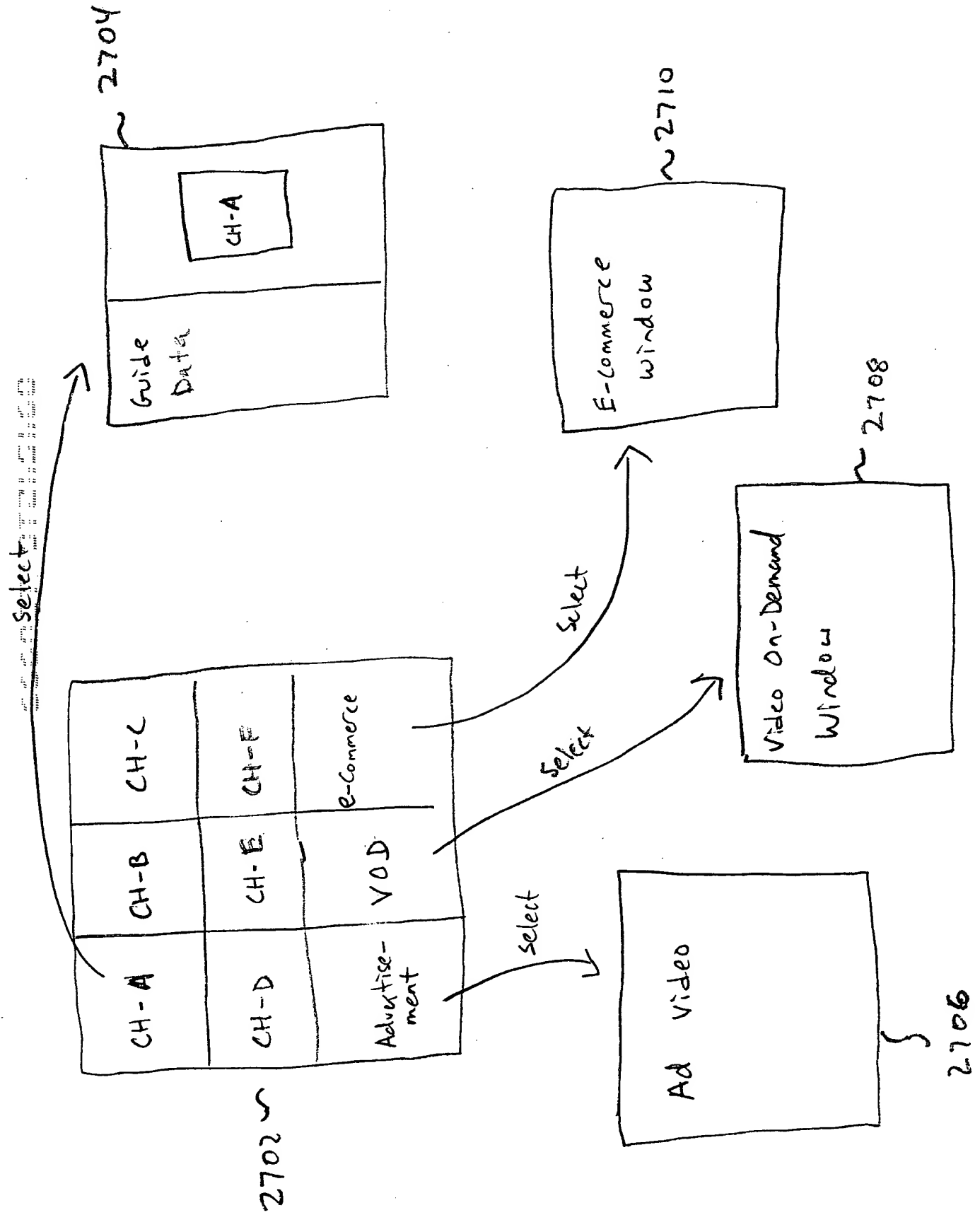


Fig. 27

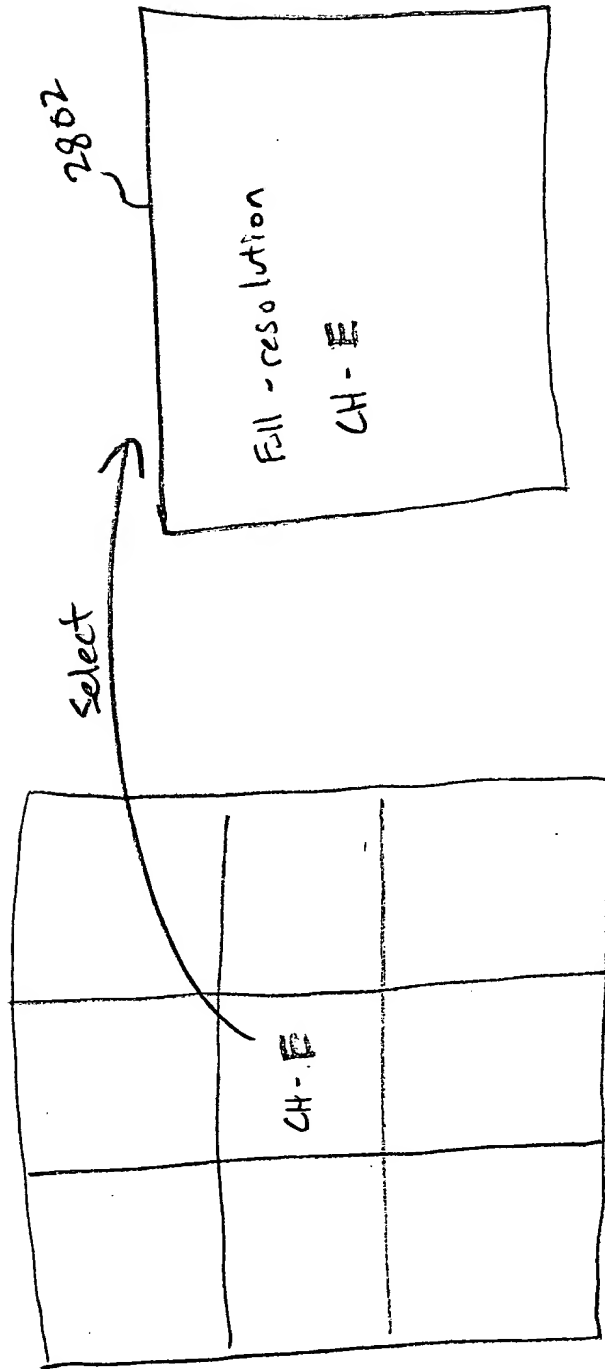


Fig. 28

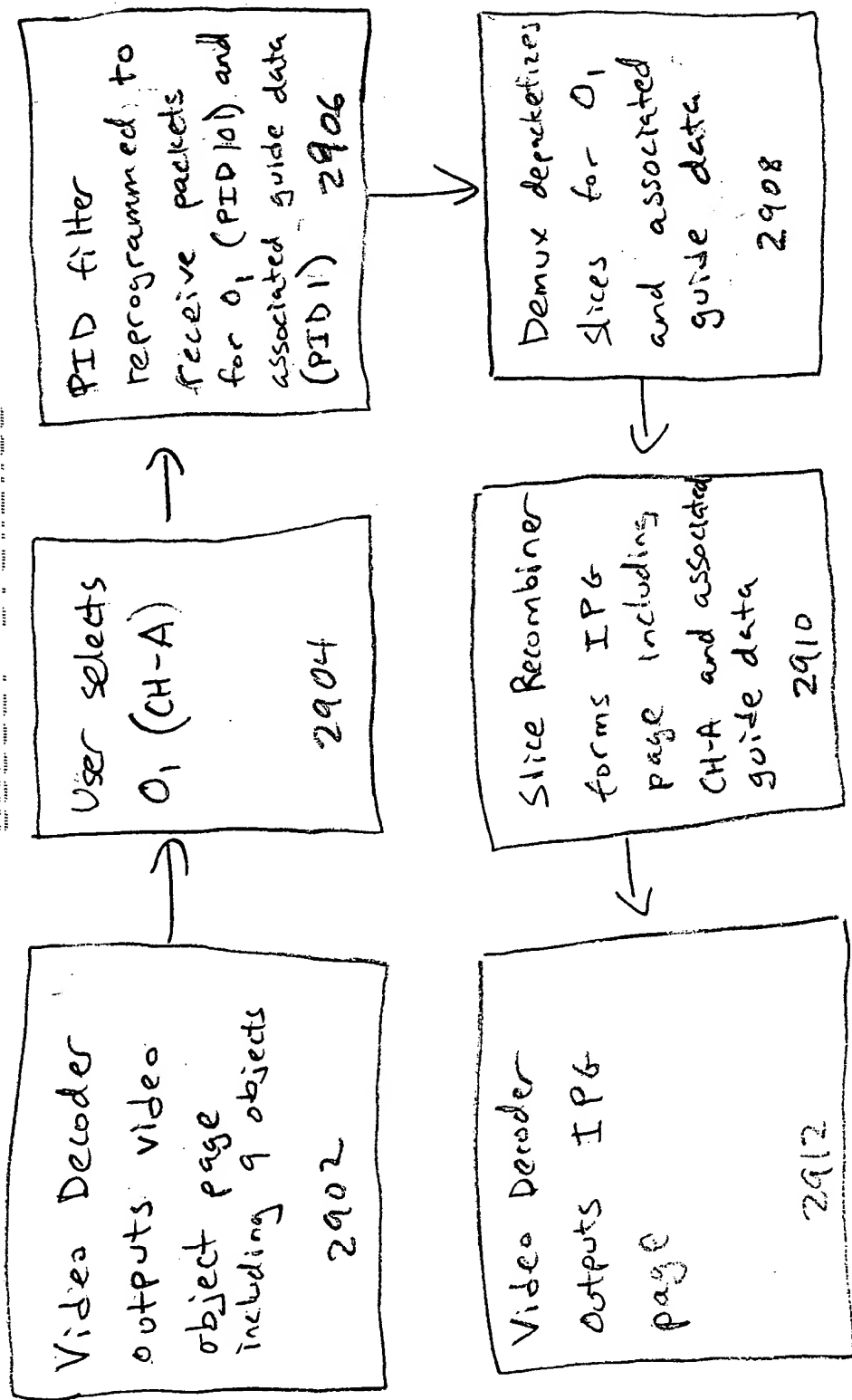
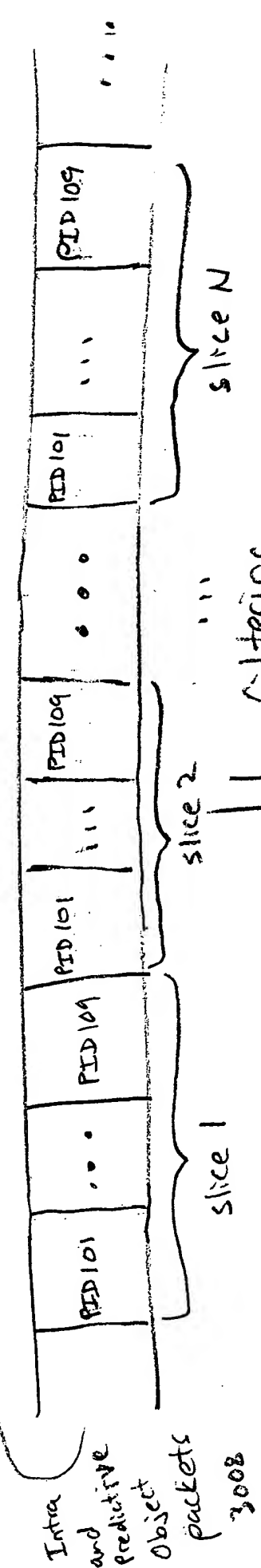
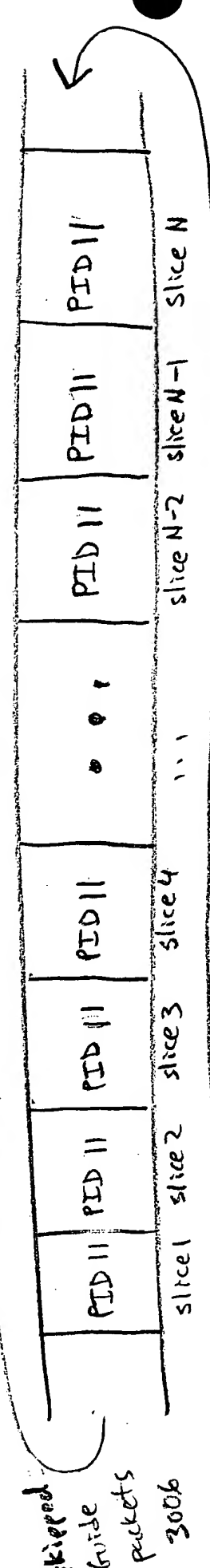
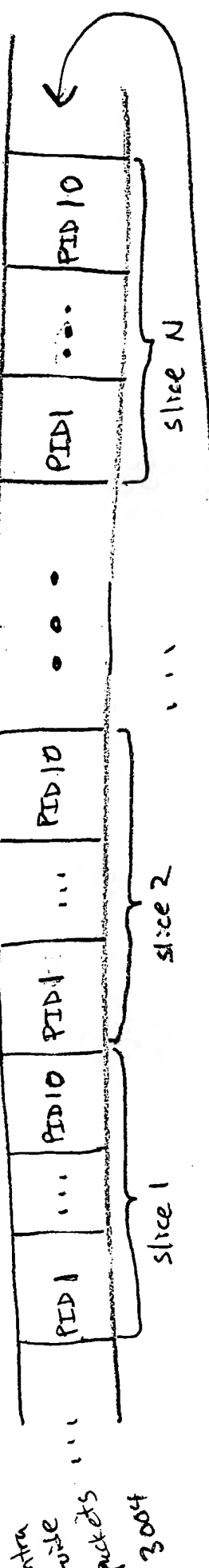


Fig. 29

3002



filtering  
3010

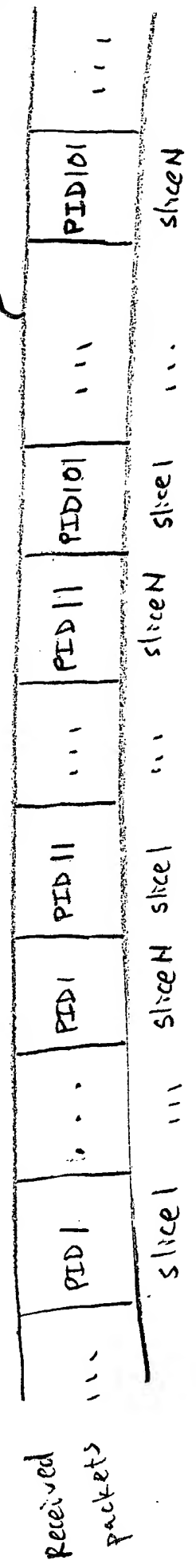
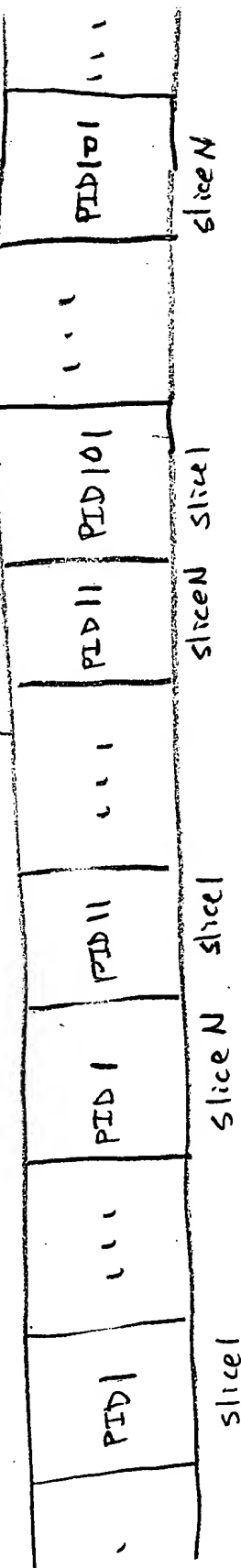


Fig. 30



Slice  
 Recombination  
 3102

PID 1 / s1	PID 101 / s1
PID 1 / s2	PID 101 / s2
PID 1 / s3	PID 101 / s3
...	
PID 1 / sN	PID 101 / sN

Intra-Coded Frame  
 3104

PID 11 / s1	PID 101 / s1
PID 11 / s2	PID 101 / s2
PID 11 / s3	PID 101 / s3
...	
PID 11 / sN	PID 101 / sN

Predictive-Coded Frames  
 3106

Fig. 31

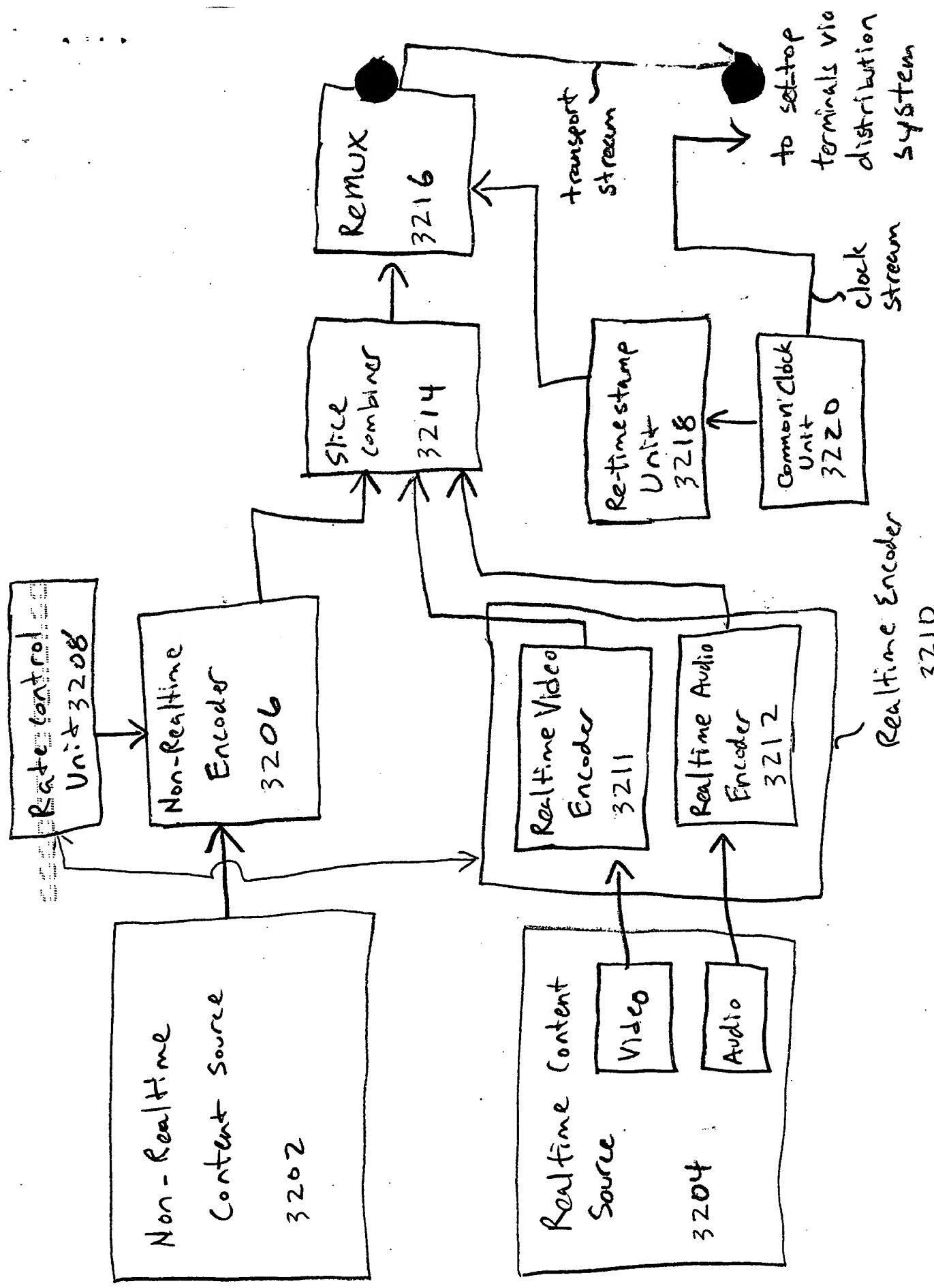


Fig. 32

Re-timestamping and Rate Control Apparatus